

- The Problem Frames
 approach
 - definition
 - (further) examples

Contex diagram vs. Problem diagram

- The diagrams we have seen so far are context diagrams, framing the problem in the real world
 - summary: domains and interfaces
- Problem diagrams supplement those with requirements
 - expressed in terms of interfaces
 - referencing the non-machine domains

Context diagram vs. Problem diagram

• Notation:



- Of course, just adding a "Requirements" bubble, connected with all the domains, does not help much
- Since we included in the context diagram all the domains of relevance for the requirements, by definition we will have arrows from Requirements to all of them

- not very useful, just adding complexity





- The classical way to manage complexity is by decomposition into sub-problems
 - by analogy: if a task is complex, divide it into simpler steps
 - in contrast: steps are sequential and distinct, subproblems are often not
- We will say more about decomposition later on; for now let us focus on simple subproblems

Example (simpler)

 Let us consider a simpler (related) problem, i.e. showing the raw values of the analog sensors' readings on the nurse station



- This is the context diagram
- What about the requirements?

Example (simpler)

 Let us consider a simpler (related) problem, i.e. showing the raw values of the analog sensors' readings on the nurse station



Writing the requirements

- But how are requirements written?
 - Not really relevant for our discussion
 - Main goal: relationships between interface phenomena of the domains must be clear
- Formality?
 - Sure, if you need the assurance and can handle it
 - Logics, automata, state diagrams, equational, ...
- Informality?
 - Sure, as long as it is rigorous enough to support implementing the specification
 - Natural language, sketches, ...

Example (simpler)

- Up to date display:
 - $\forall AD! RegisterValue(factor, v). NS! DisplayData(factor)=v$
 - Nurses' station must display the most recently read value for each devices



Example (simpler)

- Up to date display:
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Solving the problem

- We need to
 - Describe the requirements (optative description, how the customer would like the world to be)
 - Describe the domain properties (indicative description, how physical domains will react to phenomena)
 - Build the machine specification (optative description, how the machine should react at its interface)
- Once more: $S \cup D \models R$

Solving the problem

- **R Requirements:** (up to date display) ∀ *AD* ! *RegisterValue* (*factor*, *v*). *NS* ! *DisplayData* (*factor*)=*v*
- **D Domains:** (nurses' station is working) *MM* ! UpdateValue(factor, v) ⇒ NS ! DisplayData(factor)=v
- **S Specification:** (program to write) *AD* ! *RegisterValue*(*factor*, *v*) ⇒ *MM* ! *UpdateValue*(*factor*, *v*)
- Hence: $S \cup D \models R$



Solving the problem (the small print)

- Notice that what we have presented is a simplified version (for clarity)
- Not a sub-problem of the original problem
 - Some difference:
 - The original problem stated that the periods of samples where to be configured, hence it was a *pull* model
 - In this latter version, we assumed a *push* model, with the sensors sending the value: *AD* ! *RegisterValue*(*factor*, *v*)
 - In the original, causality would follow a different chain
 - More on this later on

Problem solved?

- From a purely requirements view, yes
 - The previous problem diagram contains enough information to realize the specification
 - Plus, of course, needed "technical" details

- From a humancentric view, no
 - We have not taken into account any human-related issue
 - We have solved the correctness problem
 - Did not do any elicitation really
 - How do human issues fit?

Problem solved?

- What about distribution?
 - We have ignored how different pieces of equipment interact
 - Those were really parts of a (miniature) distributed system
 - Sensors and related electronics
 - Nurses' station

- Shall we focus more on distribution here?
 - Hard to give a 'blanket' answer
 - How often do communication infrastructure break?
 - Does it introduce significant delays?
- Probably not (here)

Example (simpler): adding humans

- Extending the problem with humans
- New requirements:
 - Nurses must be aware of each patient's condition



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Connection domains

- Connection domains are characterized as:
 - They connect two other domains
 - They transfer phenomena on one interface to phenomena on another
 - They have properties that is worth modelling (otherwise, they can be omitted)
 - Failures
 - Delays
 - Filtering
 - Etc.
- Distinction is conceptual, not formal

Connection domains

- Most communication infrastructure can be considered a connection domain
- However, there are further properties of distributed systems to take into account
 - Communication is only one of them
 - What about separate memory spaces?
 - Different processing speed?
 - Different environmental conditions?
 - e.g., parts of a distributed system could sit inside the melting reactor of a nuclear power plant, others out of it

Solving the problem

- **R Requirements:** (up to date display) *DisplayedValue*(*patient*, *factor*)=*FactorEvidence*(*patient*, *factor*)
- D Domains:

. . .

- (Nurses' station is working) $MM ! UpdateValue(p, f, v) \Rightarrow NS ! DisplayedValue(p, f) = v$
- (Analog devices are working) $IP ! FactorEvidence(p, f, v) \Rightarrow AD ! RegisterValue(p, f, v)$
- (Nurses are paying attention)
- (Patients are attached to the devices)



Solving the problem

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Human domains

We have a problem here: human domains are **biddable**, not **causal**, hence we can only hope (and not guarantee) that they will behave as expected

(Not) solving the problem

- Once biddable domains come into the picture (and humans are always, *at most*, biddable), we cannot develop a specification that will guarantee $S \cup D \models R$
- Two alternatives:
 - Renounce solving the problem
 - Develop means to introduce quasi-causal behaviour in a biddable domain
- We will obtain best-effort, approximate satisfaction of the requirements (at most)

Causality and almost-causality

- Notation:
 - \models , \Rightarrow = causal entailment, implication
 - $= +, \Rightarrow =$ quasi-causal entailment, implication (best effort to make it behave as causal)
- Effectiveness of quasi-causality should be considered explicitly
 - In particular, the risk of quasi-causality being broken should be assessed
 - Mitigation and counter-measures established
 - These would usually add to requirements

Causality and quasi-causality



 Patient p presents a certain (medical) condition ⇒ [IP] IP!FactorEvidence(p,f,v) ⇒ [f] AD!RegisterValue(p,f,v) ⇒ [e] MM!UpdateValue(p,f,v) ⇒ [c] NS!DisplayedValue(p,f)=v ⇒ [g] Nurses aware of patient's condition [N]

 $MM \cup N, NS, AD, IP = R$

- How can we ensure that displaying the data on the NS will cause nurses to know of a patient condition?
- Typical HCI issue:
 - Add a second channel, beyond static display
 - Audio alarm, to be played whenever a value change
 - Blink a new value on screen for the first 5 seconds
 - Implant nurses with a microchip which will give out a moderate electrical shock when a value change
 - Separate physical location from notification
 - Provide all nurses with portable displays, so they don't need to sit at the station

- Will such devices solve the problem?
 - No, they can all fail
 - Deaf nurse (so popular among patients!)
 - Nurse distracted, does not look at screen during blink
 - Nurse faints when given electrical shock
 - Portable display's battery exhausted, or device out of reach
- Real world is always *much* more complex than we can model
 - What we can do is to understand the extent of the safe bounds for our system's operations

- Possible mitigations:
 - Louder ring tone, using induction loop, repeated alarms
 - Blink until explicitly acknowledged
 - Make sure electrical shock is not a health hazard
 - Have backup battery on board, signal when main exhausted, or provide better radio coverage
- Possible counter-measures:
 - On evidence of a changed value being ignored for some time, notify someone else through other means (e.g., message doctor)

- Possible mi
 - Louder rin alarms
 - Blink until

GUIs are only part of the story!

As shown in the example, interaction may involve multiple channels and behaviours. Never think in terms of a given GUI toolkit only (unless your problem is a very standard one, for which a known GUI-based interaction pattern is well established)!

- Make sure electrical shock is not a health hazard
- Have backup battery on board, signal when main exhausted, or provide better radio coverage
- Possible counter-measures:
 - On evidence of a changed value being ignored for some time, notify someone else through other means (e.g., message doctor)

- Can we render the communication links quasicausal as well?
 - Much harder: if a wire is cut, it's hard to pump bits through it
- We can work on the **mitigation** side
 - e.g.: ensure we have a PING or a carrier over the wire
 - So that the system can detect when the connection is broken and alert the nurses
 - OMG... alerting is quasi-causal!



biddable domains and quasi-causality

• What can we tell about how to make the ICU Patient domain quasi-causal?





State of practice

记 Motorola Software Update 01.16.08

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